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Bionanomaterials and Bioinspired Nanostructures for Selective Vapor Sensing

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# Bionanomaterials and Bioinspired Nanostructures for Selective Vapor Sensing

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## Keywords

vapor sensors, bionanomaterials, bioinspired nanostructures, multivariable individual sensors, wireless sensing, battery-independent sensor operation, distributed sensor networks, unobtrusive sensors

## Abstract

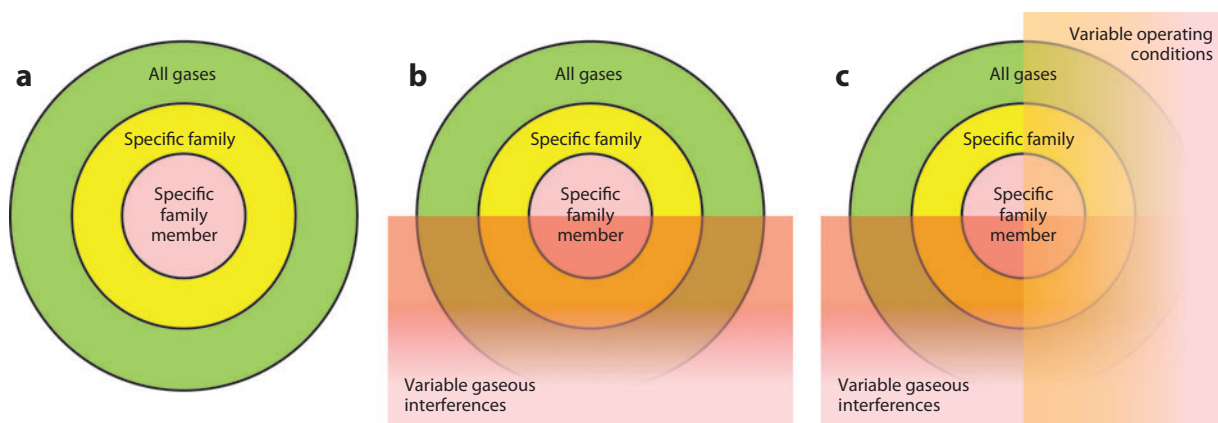
At present, monitoring of air at the workplace, in urban environments, and on battlefields; exhaled air from medical patients; air in packaged food containers; and so forth can be accomplished with different types of analytical instruments. Vapor sensors have their niche in these measurements when an unobtrusive, low-power, and cost-sensitive technical solution is required. Unfortunately, existing vapor sensors often degrade their vapor-quantitation accuracy in the presence of high levels of interferences and cannot quantitate several components in complex gas mixtures. Thus, new sensing approaches with improved sensor selectivity are required. This technological task can be accomplished by the careful design of sensing materials with new performance properties and by coupling these materials with the suitable physical transducers. This review is focused on the assessment of the capabilities of bionanomaterials and bioinspired nanostructures for selective vapor sensing. We demonstrate that these sensing materials can operate with diverse transducers based on electrical, mechanical, and optical readout principles and can provide vapor-response selectivity previously unattainable by using other sensing materials. This ability for selective vapor sensing provides opportunities to significantly impact the major directions in development and application scenarios of vapor sensors.

## 1. INTRODUCTION

Vapor and gas detection is critical for numerous everyday applications ranging from process and environmental monitoring to home, industrial, and homeland safety and security. For these and other applications, there are several types of analyzers based on different technologies, including gas chromatography, mass spectrometry, ion mobility spectrometry, and sensors. Vapor sensors are analytical devices in which a sensing material either is applied onto a suitable physical transducer or simultaneously also serves as a transducer to convert a change in a property of a sensing material into a readable form of energy (1, 2). The obtained signal from the transducer provides useful information about the concentration of species in the sample. The operational advantages of vapor sensors over other field-portable analytical instruments include (a) continuous real-time determination of the concentrations of specific sample constituents, (b) low power consumption, (c) operation without consumables, and (d) unobtrusive form factors.

Response of vapor sensors should be considered on several levels ranging from response to almost all gases and vapors, to response to only a specific vapor, and finally to response to the vapor of interest in the presence of gaseous interferences and uncontrolled operating conditions (see **Figure 1**). Most materials demonstrated for sensing are sensitive not only to target analytes, but also to a wide variety of vapors (see **Figure 1a**). The presence of gaseous interferences complicates sensor measurements (see **Figure 1b**), significantly degrading the accuracy of sensor performance. Variable or uncontrolled operating conditions, e.g., temperature fluctuations (see **Figure 1c**), further reduce the sensor accuracy.

Although the design of a sensor for a particular application is dictated by the nature and requirements of its application, it is useful to define the features that one would wish of an ideal vapor sensor. These features include high accuracy, high precision, broad dynamic range, high sensitivity, high selectivity, long-term stability, maintenance simplicity, fast response speed, low initial cost, low operation cost, response reversibility, small size, low power consumption, robustness, self-calibration, and others (1). The qualities of an ideal sensor are often weighted differently according to a particular application. For numerous applications, sensitivity, selectivity, and response speed are among the most important requirements (3, 4). Significant improvement in the



**Figure 1**

Levels of needed performance of sensor systems. (a) A sensor is sensitive to all vapors (a completely nonselective sensor), to only a specific family of vapors (a partially selective sensor), or to a specific family member of vapors (a fully selective sensor). (b) The presence of gaseous interferences complicates sensor measurements by degrading the accuracy of sensor performance. (c) Variable or uncontrolled operating conditions (e.g., temperature fluctuations) further reduce the accuracy of sensor performance.

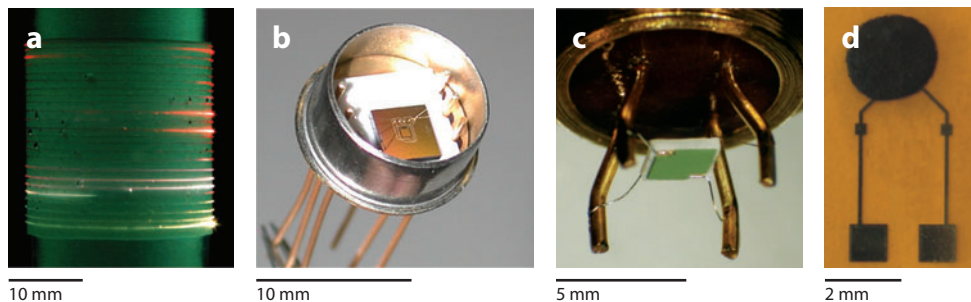
sensitivity of sensors has been demonstrated by using new sensing materials, transducer designs, and operation in vacuum or in dry carrier gas (5–7). High-surface-area sensing materials significantly increase the response speed (8). However, high selectivity remains the most significant challenge for existing sensors and has yet to be achieved in sensor design (2, 4, 9, 10). Existing vapor sensors often cannot perform highly selective vapor detection in the presence of high levels of interferences, cannot quantitate several components in gas mixtures, and cannot provide accurate vapor determinations in the presence of uncontrolled fluctuations of ambient temperature. These practical scenarios are often probable in numerous applications. Examples of present and upcoming demanding applications for sensors in complex environments include monitoring air at the workplace, in urban environments, and on battlefields; monitoring exhaled air from medical patients; monitoring air in packaged food containers; and detecting diseased agricultural crops. To meet the requirements for these and other demanding applications, new sensing approaches with improved sensor selectivity are required. This technological task can be accomplished by the careful design of sensing materials with new performance properties and by coupling these materials with the suitable physical transducers.

This review is focused on assessing the capabilities of bionanomaterials and bioinspired nanostructures for selective vapor sensing. We demonstrate that these sensing materials can operate with diverse transducers based on electrical, mechanical, and optical readout principles and can provide vapor-response selectivity previously unavailable from other sensing materials. The vapor-response selectivity of these materials is attractive for their implementation in numerous practical applications. Bionanomaterials have been explored for vapor sensing in the form of biomolecule-based sensing films and for functionalization of diverse nanomaterials such as carbon nanotubes (CNTs), graphene, semiconducting inorganic nanowires, semiconducting conjugated polymer nanotubes, and metal nanoparticles. Vapor sensing with bioinspired nanostructures also brings important vapor-response selectivity when coupled with multivariable optical transducers. These nanophotonic sensors are based on vapor responses of biological structures with future nanofabricated biomimetic designs and with bioinspired, structurally colored, colloidal crystal films. This ability for selective vapor sensing provides opportunities to significantly impact the major directions in development and application scenarios of vapor sensors.

## 2. TRANSDUCER TECHNOLOGIES

### 2.1. Transducer Types

The energy-transduction principles that are employed for chemical sensing involve radiant, mechanical, electrical, and thermal types of energy (11). Transducers based on the radiant type of energy utilize design principles based on intensity, frequency, phase, polarization, and time-domain detection methods of sensing material response and their associated transducer designs. Transducers based on the mechanical type of energy utilize design principles based on measurements of mass and viscoelastic responses of sensing materials. Examples of such transducers include cantilevers and numerous types of acoustic resonators ranging from tuning forks to thickness shear mode (TSM) resonators also known as quartz crystal microbalances (QCMs) to surface acoustic wave (SAW) resonators, bulk acoustic wave (BAW) resonators, and other devices. Transducers based on the electrical type of energy utilize different design principles to measure resistance, current, capacitance, impedance, work function, and some other electrical properties related to the electrical responses of sensing materials. Examples of such transducers include nonresonant transducers such as chemiresistors, chemicapacitors, and field effect transistors (FETs) and resonant transducers such as inductor-capacitor-resistor (LCR) resonators. Also, TSM, SAW, and other



**Figure 2**

Examples of transducers that are based on different energy-transduction principles and that have been employed for chemical sensing. (a) An example of radiant energy transduction is an intensity-based distributed fiber-optic sensor with its siloxane cladding chemically modified with an absorbing dye (shown in the photo as scattering red light; in contrast, unmodified cladding scatters white light). (b) An example of mechanical energy transduction is a micromachined cantilever with a deposited polycarbonate as a sensing material. Adapted with permission from Reference 12. (c) An example of electrical energy transduction is a resistor with a deposited metal oxide semiconducting sensing material on one side and a microheater of the sensing material on the other side of the substrate. (d) An example of thermal energy transduction is a resistor formed on a flexible polyimide foil, passivated by a layer of photo resist, and catalytically activated by  $\text{MnO}_2$ . Adapted with permission from Reference 13.

acoustic resonators can be utilized for measurements of electrical properties of sensing materials. Transducers based on the thermal type of energy utilize different design principles to measure calorimetric response of sensing materials. **Figure 2** shows representative examples of transducers that are based on different energy-transduction principles and that have been employed for chemical sensing.

## 2.2. Sensor Arrays

The requirement for sensor selectivity often conflicts with the requirement for sensor reversibility because the full reversibility of sensor response is achieved via weak interactions between the analyte and the sensing film, whereas the high selectivity of sensor response is achieved via strong interactions between the analyte vapor and the sensing film. As a result, the fundamental nature of adsorption and absorption interactions between vapors and materials typically does not provide high molecular-recognition selectivity compared with that in biomolecular interactions (2, 8).

**Table 1** summarizes the vapor-response mechanisms of some of the most widely studied types of sensing materials (6, 9, 14–25). Despite the significant diversity of mechanisms, no fully selective vapor-sensing materials are yet available. As an example, **Figure 3** illustrates typical response cross-sensitivity for different types of sensing materials toward a variety of vapors (23, 24, 26–31). A common approach to address the problem of poor selectivity of individual sensors is to build an array of partially selective sensors (32) and to process the array response by using multivariate analysis (33). In such sensor arrays, individual transducers are coated with sensing materials, and the response of the sensing material (e.g., resistance, current, capacitance, work function, mass, temperature, optical thickness, light intensity) is measured. The use of multitransducer sensor arrays based on different detection principles provides a way to further enhance response selectivity (10). Examples include cantilever-capacitor-calorimeter (34), resistor-TSM (35), capacitor-TSM (36), and resistor-SAW (37) arrays. **Figure 4** illustrates examples of some sensor arrays with different numbers of sensors and different transducers in an array (34, 38–42).

**Table 1** Response mechanisms of different sensing materials for gases and vapors (6, 9, 14–25)

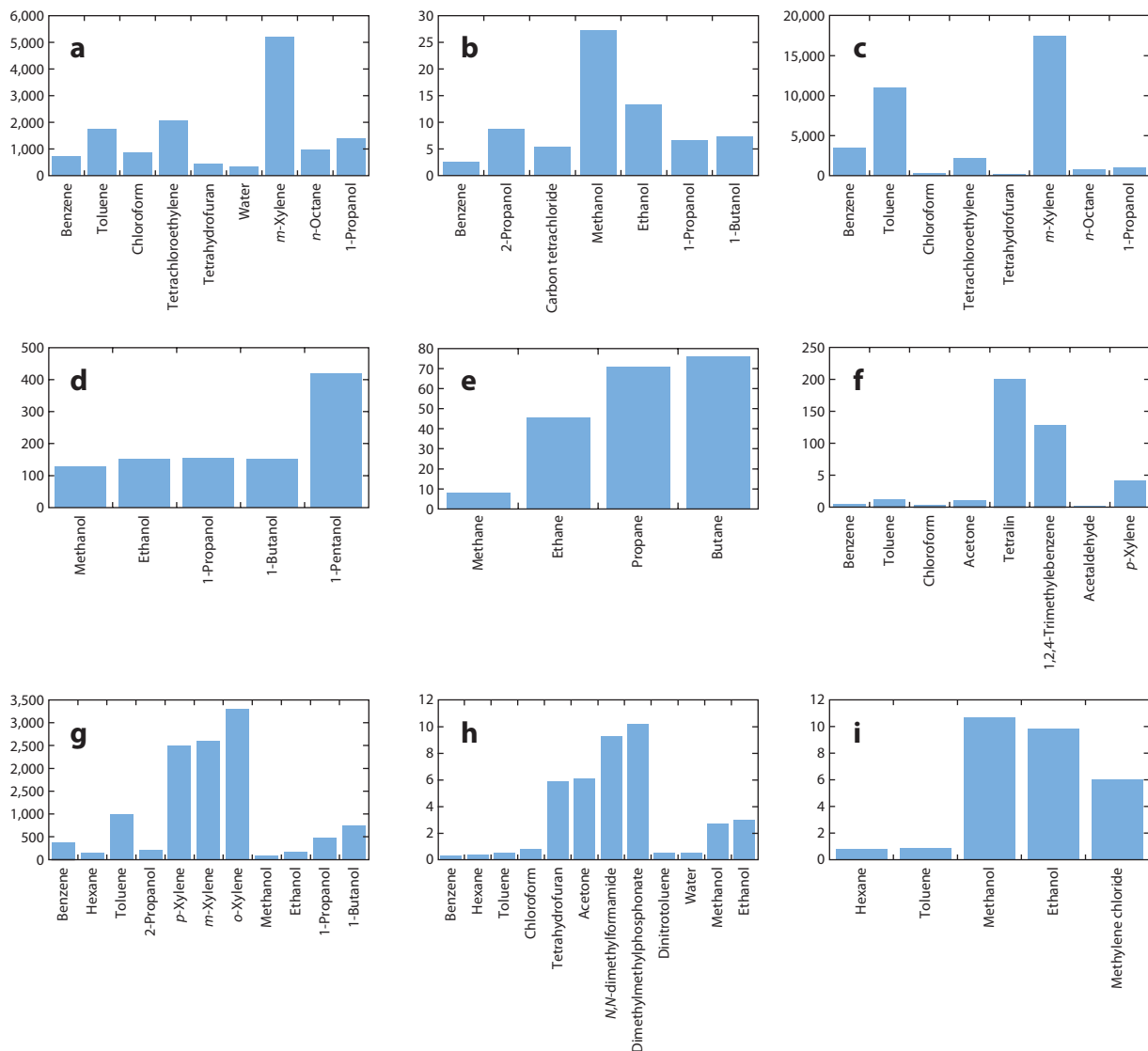
Type of sensing material	Response mechanisms	Reference(s)
Dielectric polymers	Dispersion, polarizability, dipolarity, basicity, acidity, and hydrogen bonding interactions	9
Conjugated polymers	Changes in density and charge carrier mobility, swelling, and conformation transitions of chains	14, 15
Metal porphyrins, phthalocyanines, and related macrocycles	Hydrogen bonding, polarization, polarity, metal center coordination interactions, $\pi$ stacking, and molecular arrangements	16, 17
Cavitands	Intracavity host-guest complexation with hydrogen bonding, CH- $\pi$ , and dipole-dipole as the main specific interactions	18
Zeolites	Molecular discrimination by size, shape, molecular kinetic diameter	19
Metal-organic frameworks	van der Waals interactions of the framework surface, coordination to the central metal ion, hydrogen bonding of the framework surface, size exclusion	20, 21
Monolayer-protected metal nanoparticles	Sorption of vapors in insulating regions, electron tunneling between metal cores, charge hopping along the atoms of ligand shell	22, 23
Carbon nanotubes	Charge transfer from analytes and polarization of surface adsorbates, gas-induced Schottky barrier modulation	24, 25
Graphene	Charge transfer induced by adsorption/desorption of gaseous molecules acting as electron donors or acceptors, leading to changes in conductance	6

When a sensor array response is processed by using multivariate analysis tools, the goal is to provide qualitative analysis by extracting response patterns and identifying types of detected analytes or to provide quantitative analysis of concentrations of one or several analytes (33, 43). The most widely implemented pattern-recognition technique for multivariate signals is principal-components analysis (PCA) (33). **Figure 5** summarizes the principle of data processing using PCA and the main aspects of the PCA-based pattern recognition. PCA is a robust, unsupervised technique that reduces the data dimensionality by presenting the data as the weighted sums [principal components (PCs)] of the original inputs from each sensor.

### 2.3. Multivariable Individual Sensors

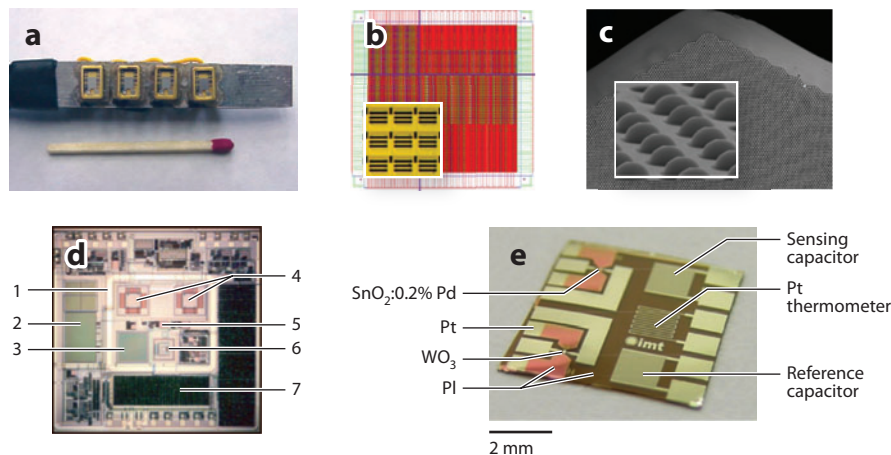
Multivariable sensors are devices that provide several partially or fully independent responses from an individual sensor. The key for such multivariable response of an individual sensor is a proper combination of a multivariable transducer with a sensing material. Different approaches have been reported for building multivariable sensors. Simultaneous measurements of capacitance and resistance of CNT sensing materials were performed, demonstrating the ability to discriminate between different vapors on the basis of their different ratios of capacitance and resistance responses (44). Multiparameter vapor sensing was also demonstrated by using FETs (45) and temperature-programmed sensors (46). Impedance spectroscopy measurements were performed on TSM (47) and interdigital (48) sensors to extract several independent parameters. Also measured were independent output parameters of individual acoustic wave transducers, for example, wave propagation velocity and attenuation (49), series-resonant frequency and resonant admittance (50), and material resistance and resonance frequency (51). Researchers described sensors based on dissipation spectroscopy that measured the magnitudes of the high-frequency conductivity changes in semiconducting sensing films related to different vapors (52, 53). Low-frequency noise spectra have also been utilized to distinguish between different vapors (54).





**Figure 3**

Typical vapor-response selectivity of different types of sensing materials. (a) Dielectric polymers. The vapor partition coefficient  $K$  of polyetherurethane is determined by using thickness shear mode (TSM) sensors. From Reference 26. (b) Conjugated polymers. Shown is the resistance response  $\Delta R/R$  (%) of polypyrrole doped with camphorsulfonic acid upon exposure to saturated vapors. From Reference 27. (c) Metal phthalocyanines. Shown is the vapor partition coefficient  $K$  of nickel phthalocyanine by using TSM sensors. From Reference 26. (d) Cavitands. The frequency shift  $\Delta F$  of phosphorus-bridged cavitand upon exposure to 3,000 ppm of vapors is measured by using TSM sensors. From Reference 28. (e) Zeolites. Potentiometric vapor response  $\Delta U$  of Pt-loaded zeolite Na-ZSM-5 upon exposure to 1,000 ppm of vapors. From Reference 29. (f) Metal-organic frameworks. Henry's constant  $K_H$  in IRMOF-1. From Reference 30. (g) Monolayer-protected metal nanoparticles. Vapor partition coefficient  $K$  of octanethiol-Au nanoparticles determined by using TSM sensors. From Reference 23. (h) Carbon nanotubes. Shown is the capacitance response  $(\Delta C/C) \times 10^{-3}$  of bare single-walled carbon nanotubes upon exposure to 0.01  $P/P_0$  of vapors. From Reference 24. (i) Graphene. Shown is the resistance response  $\Delta R/R$  (%) of reduced graphene oxide upon exposure to saturated vapors. From Reference 31. The  $y$  axes in panels  $a-i$  represent the corresponding sensor responses.



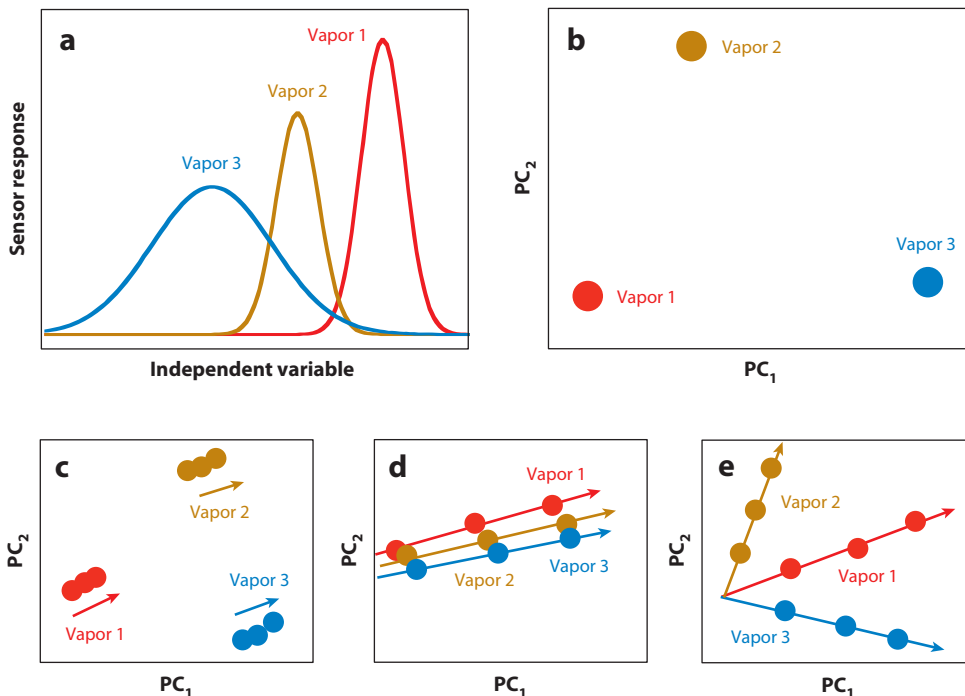
**Figure 4**

Examples of sensor arrays with different numbers of sensors and different types of transducers in an array. (a) An array of four thickness shear mode sensors for operation with polymeric sensing films. (b) An array of 4,096 interdigital electrode resistor sensors for operation with conjugated polymeric sensing films with the capability for operation with 65,536 sensors. The size of the die is  $2.1\text{ cm} \times 2.1\text{ cm}$ . The inset shows nine individual interdigital electrode resistors. Adapted with permission from Reference 39. (c) Portion of an imaging fiber-optic bundle sensor array that contains thousands of microwells etched into one face of an imaging fiber-optic bundle and filled with diverse dye-doped microspheres. The inset shows microbead sensors in etched microwells. Each individual fiber core is  $4.5\text{ }\mu\text{m}$ . Adapted with permission from Reference 41. (d) A multitransducer vapor microsensor system chip ( $7 \times 7\text{ mm}$  size) with different components that include (1) a flip-chip frame, (2) a reference capacitor, (3) a sensing capacitor, (4) a calorimetric sensor and reference, (5) a temperature sensor, (6) a mass-sensitive resonant cantilever, and (7) a digital interface. Adapted with permission from Reference 34. (e) A multitransducer vapor microsensor system on polyimide (PI) foil with two metal oxide and two capacitive gas sensors and a resistive thermometer. Adapted with permission from Reference 42.

A powerful approach for building multivariable transducers was recently developed by using a variety of resonant devices. Several examples of the resulting multivariable sensors are illustrated in **Figure 6** and utilize acoustic wave (**Figure 6a,b**) and LCR (**Figure 6c,d**) transducers (55–58) coupled with sensing materials that exhibit different response mechanisms for different species of interest. For selective analyte quantitation using individual sensors, impedance spectra of the resonator were measured, and several parameters from the measured real  $Z_{\text{re}}(f)$  and imaginary  $Z_{\text{im}}(f)$  portions of the impedance spectra were further calculated. These parameters included frequency position  $F_p$  and magnitude  $Z_p$  of  $Z_{\text{re}}(f)$ , resonant  $F_1$  and antiresonant  $F_2$  frequencies, and their respective magnitudes  $Z_1$  and  $Z_2$  of  $Z_{\text{im}}(f)$  (57, 58). By applying multivariate analysis to the impedance spectra or to the calculated parameters, quantitation of analytes and their mixtures with interferences was performed with individual sensors (59, 60).

Importantly, this approach for the improvement of sensor performance is very general. The implemented transducers include TSM (**Figure 6a**) and SAW (**Figure 6b**) devices as well as LCR resonators operating in different frequency ranges such as the radiofrequency (kilohertz to megahertz) range (**Figure 6c**) and the microwave (gigahertz) range; an LCR resonator can be a split-ring resonator (SRR) or a dual SRR (**Figure 6d**) (4, 61, 62). Operation of the LCR circuits at higher frequencies is also possible, leading to transducers operating in the optical spectral range.

Importantly, these developed LCR sensors operate not only with semiconducting materials to achieve the desired response selectivity via changes in the conductivity and capacitance of

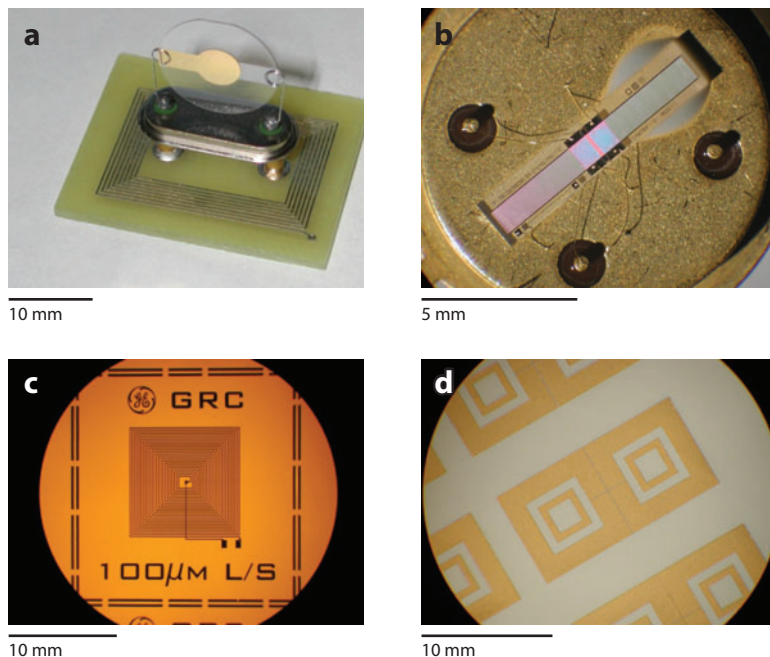


**Figure 5**

The principle of data processing using principal-components analysis (PCA) and the main aspects of PCA-based pattern recognition. (a) Three simulated Gaussian curves with variable height and width for PCA exemplary processing. (b) A scores plot of a PCA model based on the data from the three simulated Gaussian curves. (c–e) Three general scenarios of PCA scores plots: (c) poor sensitivity and good selectivity, (d) good sensitivity and poor selectivity, and (e) good sensitivity and good selectivity. PC<sub>1</sub>, PC<sub>2</sub>, and PC<sub>3</sub> denote principal components 1, 2, and 3, respectively.

semiconducting sensing films (44, 52, 63), but also with dielectric polymers (4, 59). One of these polymers, polyetherurethane (PEUT), was used to demonstrate selective detection of individual vapors with a single sensor (**Figure 7**). Sensor response depended on the dielectric constants  $\epsilon_r$  of the measured vapors as well as on  $\epsilon_r$  of the sensing film; the net capacitance either increased or decreased upon vapor exposure. For PEUT sensing films ( $\epsilon_r = 4.8$ ), the sensor capacitance increased upon exposure to vapors with the dielectric constants higher than the sensing film [e.g., tetrahydrofuran (THF) ( $\epsilon_r = 7.5$ ), ethyl acetate ( $\epsilon_r = 6.0$ ), and propanol ( $\epsilon_r = 20.1$ )], and decreased upon exposure to vapors of lower dielectric constant [e.g., benzene ( $\epsilon_r = 2.3$ )]. The individual  $F_p$ ,  $F_1$ ,  $F_2$ ,  $Z_p$ ,  $Z_1$ , and  $Z_2$  responses (**Figure 7a,b**) were analyzed by using PCA tools, and the results are shown in **Figure 7c**. This single sensor with a multivariable response was able to easily discriminate between benzene and propanol but was unable to discriminate between tetrahydrofuran and ethyl acetate at these relatively low concentrations  $P/P_0$ , where  $P$  is vapor partial pressure and  $P_0$  is the saturated vapor pressure.

Another recently demonstrated general design of the multivariable sensors was based on bio-inspired approaches and utilized dielectric resonators (**Figure 8**). One sensor concept was based on the opal-like iridescence of self-assembled photonic crystals (**Figure 8a,b**) (64). Another sensor concept was based on the iridescence of scales of *Morpho* butterflies (**Figure 8c,d**) (65). The reflectance spectra of the self-assembled photonic crystals and the butterfly scales provided



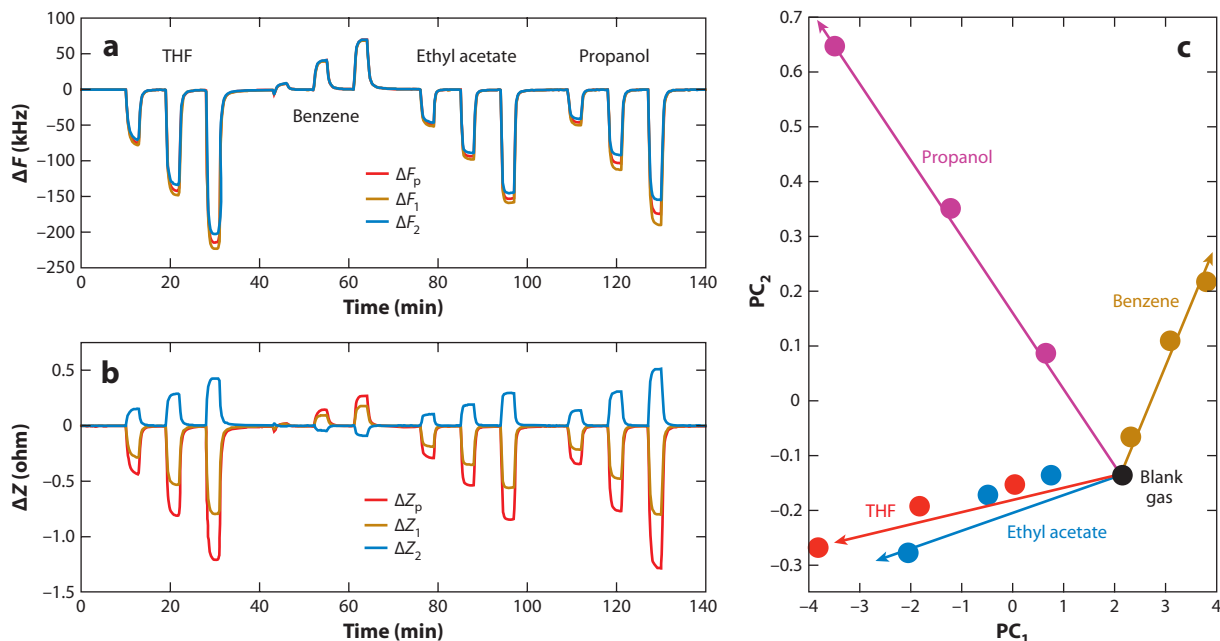
**Figure 6**

Selected examples of multivariable vapor sensors based on acoustic wave and inductor-capacitor-resistor (LCR) resonators. (a) A thickness shear mode sensor with an inductively coupled readout. (b) A surface acoustic wave sensor. (c) An LCR sensor operating in the radiofrequency range. (d) A dual split-ring resonator as an LCR sensor operating in the microwave frequency range.

information about the nature and concentration of vapors. Other bioinspired approaches for optical detection of vapors were also reported (66–69) but did not apply multivariable transduction principles.

### 3. BIONANOMATERIALS

Numerous types of biomolecules and biomolecular assemblies have been demonstrated for biosensing of large and small molecules in the aqueous phase, in which highly selective molecular recognition is facilitated by weak interactions through multivalent and cooperative binding. Examples of such bioreceptors include antibodies (70), enzymes (71), aptamers (72), phages (73), olfactory receptor–derived peptides (74), antimicrobial peptides (75), whole cells (76), cell-derived nanovesicles (77), olfactory receptors (78), odorant-binding proteins (79), olfactory neurons (80), carbohydrates (81), and oligosaccharides (82). While applying bioreceptors for the vapor-phase recognition of small molecules and odorants, one should keep in mind that the nature of molecular interactions between the native biomolecules and analytes in the aqueous phase could be altered in the vapor phase. Initial research on the applications of biological molecules as vapor-phase sensing materials goes back to the 1980s (83). At present, vapor-phase sensing using sequence-specific biomolecules such as oligopeptides (84–86) and nucleic acids (87) as well as antibodies (88), lipids (89–92), and amino acids (93) is attracting the interest of a growing number of researchers. The two broad directions in this research area are the use of biomolecules directly as sensing films on physical transducers and as selective moieties for the functionalization of signal-transducing nanomaterials.



**Figure 7**

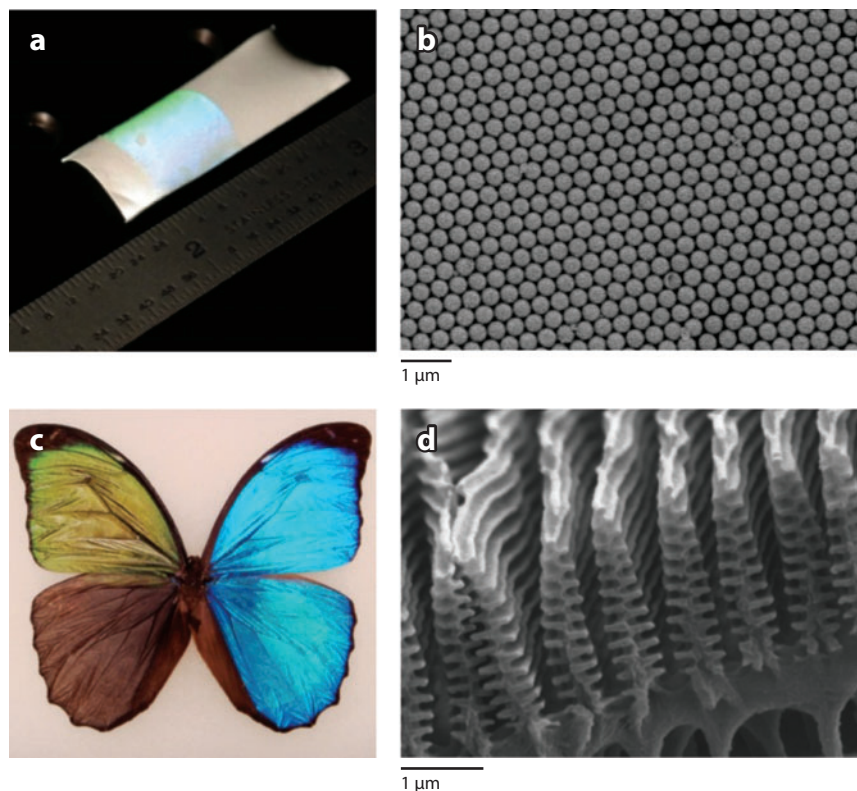
The ability to discriminate between individual vapors [tetrahydrofuran (THF), benzene, ethyl acetate, and propanol] using a multivariable transducer with a dielectric polyetherurethane film. Individual sensor responses (a)  $F_p$ ,  $F_1$ ,  $F_2$  and (b)  $Z_p$ ,  $Z_1$ , and  $Z_2$  and (c) scores plot of a model of an individual sensor response using principal-components analysis (PCA). Concentrations of vapors are 0, 0.04, 0.07, and 0.11  $P/P_0$  (THF); 0, 0.09, 0.18, and 0.27  $P/P_0$  (benzene); and 0, 0.05, 0.11, and 0.16  $P/P_0$  (ethyl acetate and propanol).

### 3.1. Biomolecule-Based Films

The rationale for using biomolecules as vapor-sensing films comes from odorant receptor proteins (94) and, in general, from receptors in living cells (95). Different resonant transducers such as TSM (89, 90, 92, 96), SAW (88, 97), and microcantilever resonators (98) were implemented for the detection of vapor responses by using biomolecule-sensing materials. It is possible to compute selective target-binding ability of artificial oligopeptides (84, 85). Thus, artificial oligopeptides were computationally designed to mimic the highly selective aryl hydrocarbon receptor-binding site in living cells (84). The Phe-Gln-Gly backbone of this receptor strongly binds to dioxins and was chosen as the basis for selection of a binding pocket on the basis of amino acid motifs for computational screening of a library of artificial dioxin receptors. Several pentapeptide sequences were computationally identified and synthesized with two terminal cysteine residues. These cysteine residues were used to covalently attach the peptides onto TSM resonators and were able to detect dioxins down to low-parts-per-billion levels. Experimentally determined selectivity against the dioxin vapor correlated well with the calculated binding energy of receptors.

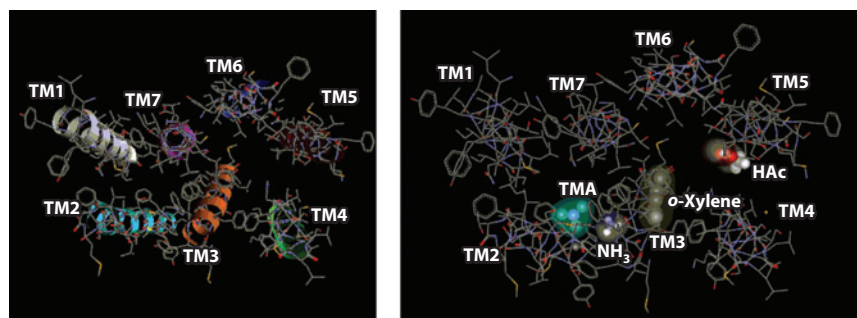
Peptides that resemble binding sites of human olfactory receptor protein have also been identified, synthesized, and tested for their responses to target vapors and interferences (85). From the tertiary structure of olfactory receptors, the odorant-binding domains were expected to be localized on the surface of the transmembrane (TM) domains within an  $\alpha$ -helix structure (99). The tertiary structure of the human olfactory receptor protein P30953 was modeled (Figure 9a), followed by computer docking simulations to find binding sites between the model structure and several target vapors, including trimethylamine, ammonia, acetic acid, and *o*-xylene (Figure 9b)





**Figure 8**

Selected examples of multivariable vapor sensors based on bioinspired dielectric resonators. (a) A photo of a structurally colored composite core/shell colloidal crystal film. (b) Scanning electron microscope (SEM) image of the photonic nanostructure. Panels *a* and *b* are adapted with permission from Reference 64. (c) Photo of an iridescent *Morpho* butterfly demonstrating color changes upon exposure to liquids of different refractive indexes,  $n$ . The top left wing was exposed to ethanol solvent ( $n = 1.362$ ), and the bottom left wing was exposed to toluene solvent ( $n = 1.497$ ). (d) An SEM image of the photonic *Morpho* nanostructure.



**Figure 9**

Binding of diverse vapors to the P30953 human olfactory receptor. (a) Molecular model of the tertiary structure of the receptor. (b) Four identified sites responsible for binding of trimethylamine (TMA), ammonia ( $\text{NH}_3$ ), acetic acid (HAc), and *o*-xylene vapors. TM denotes transmembrane. Adapted with permission from Reference 85.

(85). Ligand-binding sequences were identified as those with the most exothermic interactions with the target vapors. Four sites for binding target vapors were located within TM  $\alpha$ -helices TM2, TM3, and TM5 (see **Figure 9b**). Polypeptides corresponding to the selective portions of these binding sites were designed, synthesized, and attached to TSM transducers for vapor testing. Each polypeptide demonstrated a strong preferential response to its corresponding vapors with a 3–5-fold-lower response to interferences (85).

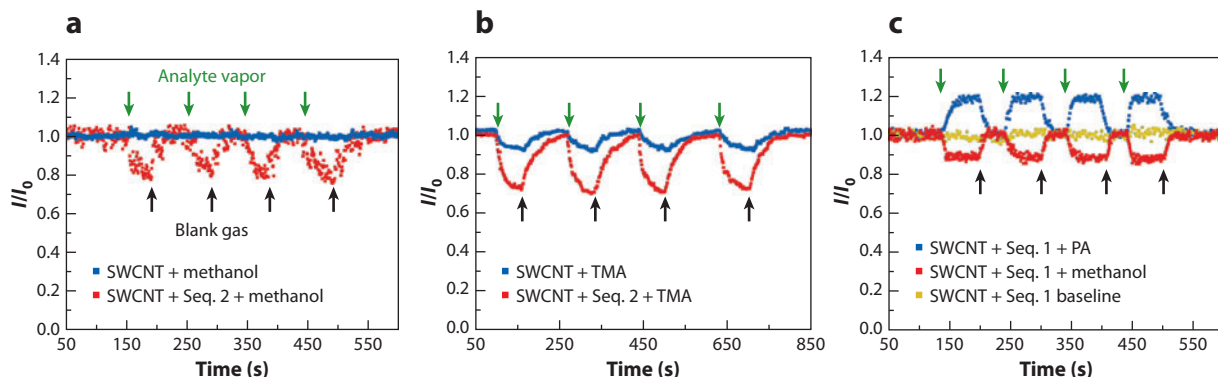
Polypeptide sequences with affinity to a wide range of materials were selected by using combinatorial chemistry techniques such as bacterial cell surface and phage-display techniques (100–102). Phage display has been utilized to identify peptides that specifically recognize desired analytes at the molecular level with specific recognition motifs (103). Using mutational analysis, investigators showed that polypeptides with specific recognition motifs can bind trinitrotoluene (TNT) and dinitrotoluene (DNT) vapors through multivalent interactions of these vapors with key side-chain amino acids. DNT-binding peptide receptors were further conjugated to an oligo(ethylene glycol) hydrogel for vapor-phase testing. Experimental results of a vapor-phase binding assay for a DNT-specific film demonstrated a fourfold increase in the partition coefficient for DNT over TNT vapor. Vapor-phase binding performance was attributed to the ability of the oligo(ethylene glycol) hydrogel to maintain the conformation and selectivity of biomolecules. These results demonstrated a successful translation of binding peptide receptors screened in liquid to selective vapor-phase sensing.

Lipid and lipid-like sensing films have also been extensively used for vapor sensing because a wide variety of volatile organic compounds are soluble in lipids (104). This vapor solubility of lipids and lipid-like molecules opens up the possibility to use these molecules for vapor sensing directly attached to a transducer (83, 89), formulated into a polymer matrix (90), formed as mixed-lipid films (91), or grafted with polymers (92).

Deposition of films containing biological molecules for vapor sensing has been explored not only using traditional methods such as immobilization from solution onto transducers (84) and incorporation of biomolecules into hydrogel matrices (103), but also using plasma deposition (96, 105) and molecular effusion (93). Plasma deposition was performed by radio-frequency sputtering to produce films composed of random peptide sequences formed by plasma reactions of individual amino acids during deposition (106). These moderate plasmas were used for the preparation of amino acid films for vapor sensing on the basis of solvation effects and were measured by using TSM resonators (96, 105). These films had a hydrophilic structure that gave them a high affinity for polar solvent vapors (106). The plasma-polymerized films contained unsaturated carbon moieties available for interactions with small organic molecules using  $\pi$ -electrons and unpaired electrons. In addition, the unsaturated radical sites in the carbon networks were suitable for enhancement of mobility of highly cross-linked carbon networks, making them effective at solvating small organic molecules (107). The effects of adsorbed/absorbed water on the response of these plasma polymer films on TSM resonators were further explored (96). Water sorbed on these films before chemical exposure played a significant role involving hydrophilic/hydrophobic interactions between investigated vapors, sorbed water, and the sensing films.

### 3.2. Biomolecule-Functionalized Nanomaterials

Diverse nanomaterial types such as CNTs, graphene, semiconducting inorganic nanowires, semiconducting conjugated polymer nanotubes, and metal nanoparticles have been used as transducing nanomaterial elements and have been functionalized with biomolecules (108–114). Biomolecules implemented for the functionalization of nanomaterials include single-stranded DNA (109), single-stranded RNA (115), peptides (114, 116), and olfactory receptor proteins



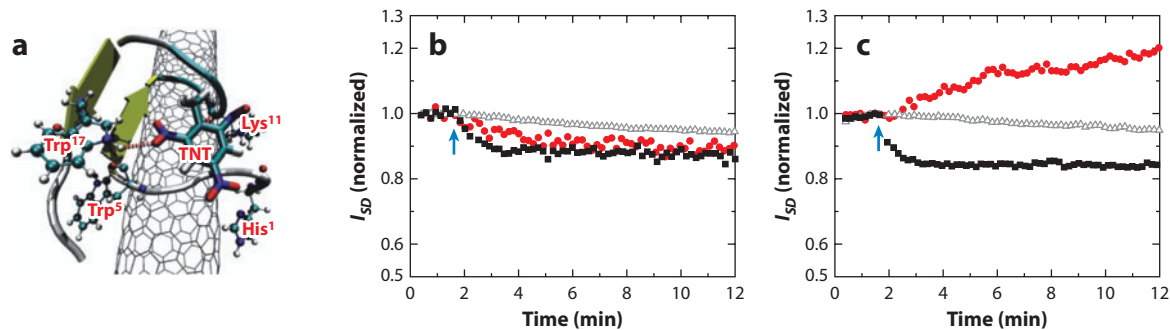
**Figure 10**

Response of field effect transistor transducers with DNA-functionalized single-walled carbon nanotubes (SWCNTs) to diverse vapors. The sensor current was normalized to the sensor response in blank air. (a) The response of bare (blue points) and functionalized (red points) SWCNTs to 4,000 ppm of methanol. DNA sequence: 5' CTT CTG TCT TGA TGT TTG TCA AAC 3'. (b) Response of bare (blue points) and functionalized (red points) SWCNTs to 20,000 ppm of trimethylamine. DNA sequence: 5' CTT CTG TCT TGA TGT TTG TCA AAC 3'. (c) Response of functionalized SWCNTs to 150 ppm of propionic acid (blue points) and 4,000 ppm of methanol (red points), with the current baseline shown with yellow points. DNA sequence: 5' GAG TCT GTG GAG GAG GTA GTC 3'. Green and black arrows in panels a–c show the introduction of an analyte vapor and a blank gas, respectively. Abbreviations: PA, propionic acid; TMA, trimethylamine. Adapted with permission from Reference 109.

(117). Different physical transducers such as FETs (108, 109) and resonators (118) have been implemented for the detection of vapor responses. Such a combination of biomolecule-based sensing moieties and the different types of transducing nanomaterials and physical transducers promises to enhance vapor selectivity compared with sensing by using more traditional sensing materials.

At present, CNTs and graphene are the most popular carbon allotropes under investigation as vapor-sensing materials (4). Unlike other sensing materials, all atoms in CNTs and graphene are surface atoms; thus, electron transport through these materials can be efficiently modulated by the environment around these atoms, including adsorbed vapor molecules. However, unless properly functionalized, these materials suffer from nonselective vapor responses. Inspired by the covalent and noncovalent functionalization of CNTs with biomolecules (119, 120) applicable for biosensing in the aqueous phase, functionalization of CNTs with biomolecules to perform vapor-phase sensing has also attracted significant attention. Single-stranded DNA-functionalized CNT films on FET transducers responded to vapors that did not cause a detectable conductivity change in bare CNT devices (109). Responses were reversible and different in direction and magnitude for different vapors and were tuned by choosing the base sequence of DNA molecules (see **Figure 10**) (109). DNA-functionalized sensors have been further used for the detection of a homologous series of aldehydes and carboxylic acids commonly found in human breath and other body emanations (121). To better understand the nature of DNA-CNT self-assembly during the functionalization of sensing films, the DNA base–CNT binding free energies were computed for all four DNA bases in aqueous solution at room temperature (122). The affinities of the DNA bases for CNT binding followed the trend  $G > A > T > C$ , with the base–CNT interactions dominated by  $\pi$ – $\pi$  stacking interactions with a solvent. CNT–DNA films deposited on resonant transducers were further demonstrated for the detection of DNT and dimethyl methylphosphonate (DMMP) (118). The selectivity of vapor determinations was further tested not only with CNT–DNA films but also with CNT–RNA films (115). These studies demonstrated the ability of these films deposited





**Figure 11**

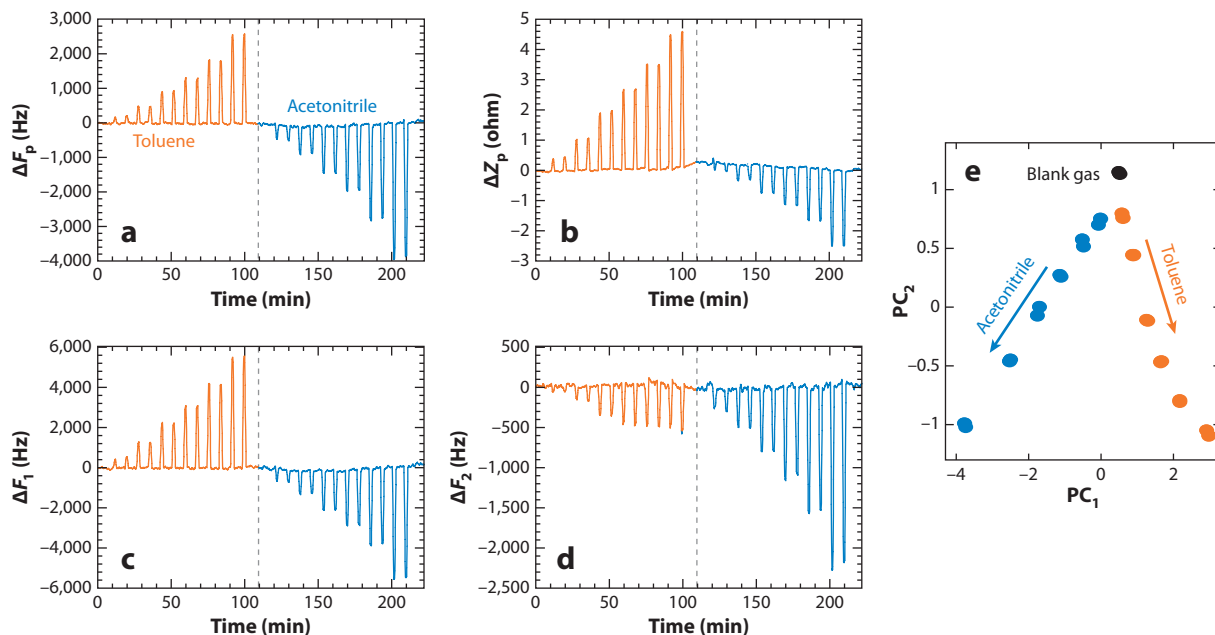
Peptide-functionalized single-walled carbon nanotubes (SWCNTs) for the detection of explosives. (a) Computational model of TNT binding to a PIASPIC-SWCNT hybrid through a H bond with Trp<sup>17</sup> and a  $\pi$ - $\pi$  interaction with the SWCNT surface. Response of (b) bare SWCNT and (c) PIASPIC-coated SWCNT transducer to TNT (red circles), RDX (gray triangles), and HPT (black squares). Blue arrows in panels b and c show introduction of analyte vapors. Abbreviations: HPT, 2-heptanone; RDX, cyclotrimethylenetrinitramine; TNT, trinitrotoluene. Adapted with permission from Reference 108.

onto FETs to discriminate between structural isomers, pairs of enantiomers, and members of a homologous series of vapor-phase analytes differing by single methylene units.

Peptides have also been employed for the functionalization of CNTs (108). Peptide vapor-recognition elements were rationally designed to perform two functions at once: noncovalent attachment to CNTs and binding to TNT as the model vapor analyte (123). The peptide-recognition elements contained two domains: a TNT-binding domain derived from the binding pocket of the honeybee odor-binding protein and a CNT-binding peptide identified from the phage peptide display library. The odor-binding protein contained a C-terminal tail fragment that binds to pheromones and other chemical targets. Four amino acids residues (Trp-Phe-Val-Ile) at the C terminus played an important role in binding to TNT. Computations of interactions between the peptide-CNT hybrid and three different chemical agents [TNT, cyclotrimethylenetrinitramine (RDX), and 2-heptanone (HPT)] demonstrated that RDX and HPT did not bind strongly to the peptide. However, TNT bound to the peptide via the nitro group of TNT, forming a hydrogen bond with Trp<sup>17</sup>, whereas the ring of TNT stacked on the surface of the CNT (see **Figure 11a**), providing a binding motif for TNT to the peptide-CNT hybrid (108). The bare CNT and peptide-CNT sensors were further exposed to TNT, RDX, and HPT vapors (see **Figure 11b,c**). The peptide-functionalized CNT-FET exhibited a selective response to TNT, as evidenced by the signal increase upon exposure to TNT, whereas the bare CNT-FET responded with a signal decrease. RDX and HPT vapor exposures showed no selectivity because the signal changes were similar for both bare and functionalized SWCNT-FET devices.

Single-stranded DNA molecules that were initially applied to functionalize CNTs (109) were further applied to functionalize graphene for the detection of DMMP and propionic acid (110). For both model analyte vapors, the current response of clean graphene was very low and barely detectable above system noise. After coating with single-stranded DNA, 5–50% response enhancements were observed. Similar to the role of single-stranded DNA-CNT sensors (109), the role of the single-stranded DNA was to concentrate water and analyte molecules near the otherwise chemically inert and hydrophobic conduction channel and, in this way, to increase the current response compared with that of bare graphene.

Besides carbon allotropes such as CNTs and graphene, other organic nanomaterials have also been implemented for functionalization with biomolecules for vapor sensing. Carboxylated



**Figure 12**

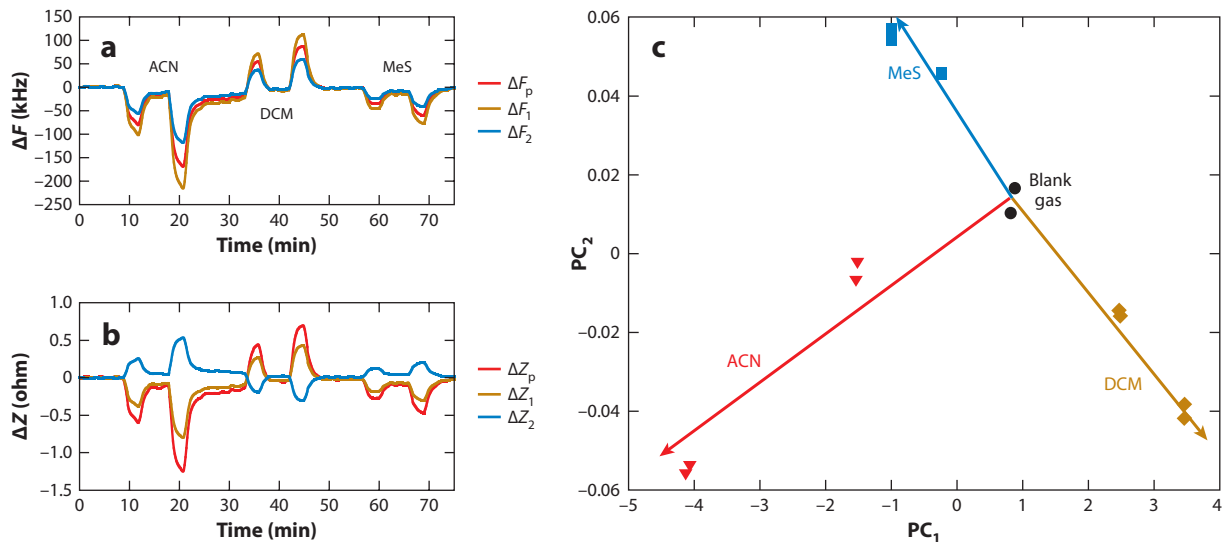
Response of an individual multivariable sensor to representative vapors (toluene and acetonitrile). Panels *a–d* show  $F_p$ ,  $Z_p$ ,  $F_1$ , and  $F_2$  responses, respectively. Concentrations of vapors are 0, 0.02, 0.04, 0.07, 0.10, 0.15, and 0.2  $P/P_0$ . The sensor is exposed to replicate  $n = 2$  concentrations of each vapor. (*e*) The designed response diversity of a single multivariable sensor to two representative vapors (toluene and acetonitrile). Shown is a scores plot of the first two principal components (PCs) of a principal-components-analysis model. Adapted with permission from Reference 59.

polypyrrole nanowires were functionalized with human olfactory receptor protein for the detection of gaseous odorants such as helional at concentrations as low as 0.02 parts per trillion (111).

Inorganic semiconducting nanomaterials have also been implemented for functionalization with biomolecules for vapor sensing. Silicon nanowires were used as a substrate for covalent attachment of polypeptides for studies of vapor-phase responses to ammonia and acetic acid by using a FET transducer (112). Selectivity of peptides to ammonia and acetic acid in dry carrier gas was achieved from the combination of acid/base reactivity and the molecular structure of peptides.

The biomolecular functionalization of metal nanoparticles for vapor sensing is much less explored than the biofunctionalization of CNTs, graphene, and nanowires. Typically, monolayer-capped metal nanoparticles are employed with resistor (124), capacitor (125), and TSM (22) transducers. With resistor and capacitor transducers, the film resistance and capacitor changes are related to (*a*) electron tunneling between metal cores through the dielectric ligand shell and to (*b*) charge hopping along the atoms of the dielectric ligand shell (23). With TSM transducers, the mass change of the film is related to vapor sorption into the dielectric ligand shell of the monolayer-capped metal nanoparticles (22). Sensor response diversity is achieved by designing different ligands for metal nanoparticles with soft and rigid linkers. The soft linkers change their length as a function of the amount of sorbed vapor. Rigid linkers restrain swelling of sensing films and boost the effects of analyte-dependent changes of the dielectric constant of the film.

To demonstrate performance capability of multivariable sensors with monolayer-capped metal nanoparticles, **Figure 12** illustrates an LCR sensor response with an organothiols-functionalized metal nanoparticle film by using toluene and acetonitrile (ACN) as model vapors (59). Four



**Figure 13**

Discrimination of vapors using an individual multivariable resonant inductor-capacitor-resistor transducer with A3 peptide-capped gold nanoparticles. (a) Sensor responses  $F_p$ ,  $F_1$ , and  $F_2$ . (b) Sensor responses  $Z_p$ ,  $Z_1$ , and  $Z_2$ . (c) Scores plot of a principal-components-analysis (PCA) model of a sensor response with replicate ( $n = 2$ ) data points for each concentration. The first two principal components (PCs) of the built PCA model of the response of the A3-Au nanoparticle material to dichloromethane (DCM), acetonitrile (ACN), and methyl salicylate (MeS) vapors included more than 99% of the total variance from the data set. Concentrations of vapors were 0.044 and 0.089  $P/P_0$ . The water vapor background was at  $P/P_0 = 0.18$ . Adapted from Reference 113.

measured parameters,  $F_p$ ,  $Z_p$ ,  $F_1$ , and  $F_2$ , were extracted from the measured resonance impedance of the sensor (**Figure 12a–d**) and provided a strong response pattern of sensor upon exposure to these two vapors. This response diversity was pronounced in the response direction and magnitude for each vapor. For example, the  $F_p$ ,  $F_1$ , and  $Z_p$  responses had opposite directions for two vapors, whereas the  $F_2$  response showed a similar direction. Response magnitudes also varied significantly in the measured  $F_p$ ,  $Z_p$ ,  $F_1$ , and  $F_2$  parameters. In particular, the  $Z_p$  response to toluene was approximately twofold stronger than that to ACN. At the same time, the  $F_2$  response to toluene was threefold weaker than that to ACN. This response diversity was due to the nature of the sensing film and sensor design. The response pattern from this single sensor was further analyzed by using PCA (**Figure 12e**). These results illustrate strong discrimination between these two vapors obtained with this single sensor.

The applicability of biological capping ligands to gold nanoparticles was recently demonstrated for selective vapor detection through the use of an individual multivariable LCR transducer and the A3 peptide AYSSGAPPMPFF as the biological capping ligand (113). As model analytes, toxic vapors and chemical warfare agent simulants, such as ACN, dichloromethane (DCM), and methyl salicylate (MeS), were used (**Figure 13**). The direction of the sensor response to DCM was opposite of that of the response to MeS vapor (**Figure 13a,b**), even though DCM has a dielectric constant  $\epsilon_r = 9.1$ , which is close to that of MeS ( $\epsilon_r = 9.0$ ). However, MeS is much bulkier than DCM, and this increased bulkiness may therefore affect the rigidity of the linker differently, as reflected in the measured resonant spectral response. Results of multivariate PCA analysis (**Figure 13c**) illustrated the discrimination ability provided by this single A3-Au nanoparticle material. The PCA model was built by using six ( $F_p$ ,  $F_1$ ,  $F_2$ ,  $Z_p$ ,  $Z_1$ , and  $Z_2$ ) responses from the sensor. The single multivariable sensor was able to discriminate three types of vapors, including DCM and

**Table 2** Mechanisms of structural coloration in animals (131–136)

Scattering	Interference	Diffraction	Combined effects
<ul style="list-style-type: none"> <li>■ Wing scales of <i>Papilio zalmoxis</i> butterfly</li> <li>■ Wing scales of <i>Parides sesostris</i> butterfly</li> <li>■ Abdomen of <i>Amenia</i> fly</li> <li>■ Cuticle of <i>Orthetrum caledonicum</i> dragonfly</li> <li>■ Skin of <i>Octopus bimaculatus</i> cephalopod marine mollusk</li> <li>■ Wings of <i>Libellula pulchella</i> dragonfly</li> </ul>	<ul style="list-style-type: none"> <li>■ Cicindelid cuticle of tiger beetles</li> <li>■ Golden pupae of danaine butterflies</li> <li>■ Cuticle of <i>Limnadia</i> clam shrimp</li> <li>■ Cuticle of a swimming paddle of <i>Ovalipes molleri</i> crab</li> <li>■ Eyes of <i>Pecten</i> scallop</li> <li>■ Neck features of rock dove</li> </ul>	<ul style="list-style-type: none"> <li>■ Wing scales of green hairstreak (<i>Callophrys rubi</i>) butterfly</li> <li>■ Antenna of <i>Azygocypridina lowryi</i> seed shrimp</li> <li>■ Junctions between rows of cells in indigo snakes</li> <li>■ Elytra of burying and gyrinid beetles</li> <li>■ Seta of <i>Lobochesis longiseta</i> polychaete worms</li> <li>■ Blazed gratings on wing scales of <i>Plusia argentifera</i> moth</li> </ul>	<ul style="list-style-type: none"> <li>■ Surface of elytra of male beetles <i>Chlorophila obscuripennis</i> comprises a sculpted multilayer resulting in blue iridescence from regularly spaced indentations and in green iridescence from the ridges surrounding the indentations</li> <li>■ Wing scales of <i>Morpho</i> butterflies exhibit combined diffraction and interference optical effects due to the coexistence of a periodic ridge structure with multilayers of lamella</li> </ul>

MeS vapors, with very similar dielectric constants. This new type of sensing materials can provide numerous opportunities for tailoring the vapor-response selectivity on the basis of the diversity of the amino acid composition of the peptides and by modulating the nature of peptide-nanoparticle interaction through designed combinations of hydrophobic and hydrophilic amino acids.

## 4. VAPOR SENSING WITH BIOINSPIRED NANOSTRUCTURES

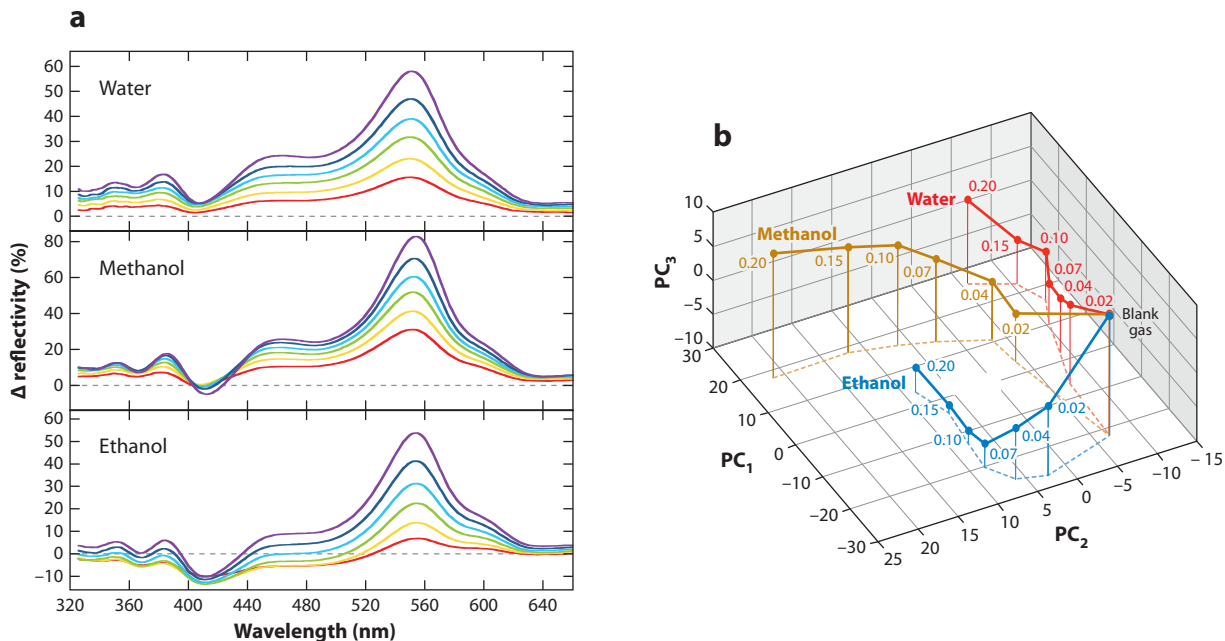
Numerous natural biological nanostructures have become the focus of growing attention for sensing applications. This interest is driven by the design features of these nanostructures that often provide geometries that are difficult or impossible to reproduce by using existing nanofabrication tools. Reported transduction principles using bioinspired nanostructures include optical (65–69, 126–128) and electrical (129, 130) transducers.

Numerous biological structures exhibit structural color based on the formation of natural photonic crystals. These photonic crystals are 1-D, 2-D, and even 3-D structures (131) and are related to a phenomenon of structural color across the animal kingdom that has been under development for more than 500 million years (132). **Table 2** presents examples of natural photonic structures that demonstrate different types of interactions with light such as scattering, diffraction, interference, and their combination (131–136). These results illustrate a vast diversity of approaches taken by natural structures to produce structural colors.

Some photonic structures in nature exhibit intrinsic vapor responses. For example, a *Dynastes hercules* beetle displays a diffractive hygrochromic effect, changing its color from green to black upon an increase in the moisture content in air above 80% (137). Several photonic natural structures, such as scales of butterflies (65–67, 138), scales of beetles (137), and bird feathers (68), have been studied for their vapor responses, with the goal of exploring the physics of the optical effects, selectivity, and sensitivity of vapor responses.

### 4.1. Vapor Responses of Biological Structures

Recently, iridescent scales of *Morpho* butterflies were demonstrated as “sensing materials” that provided an unexpected diverse optical response to different vapors (65). In these butterfly scales, the lamellae of the scale ridges act as multilayer interferometric nanoreflectors, whereas the ridges



**Figure 14**

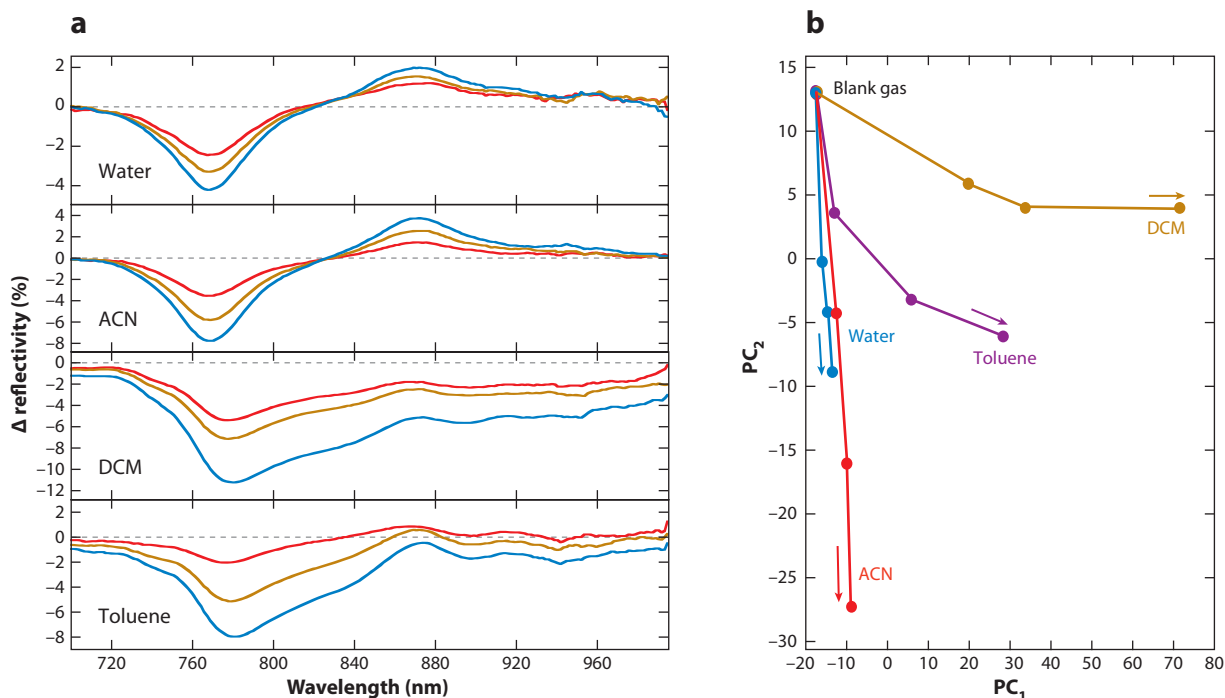
Analysis of selectivity of spectral response of the photonic structure of *Morpho sulkowskyi* to different vapors. (a) Differential reflectance spectra upon exposure to water, methanol, and ethanol vapors of increasing partial pressure ranging from 0 to 0.2  $P/P_0$ . Vapor concentrations were 0 (black lines), 0.02 (red curves), 0.04 (yellow curves), 0.07 (green curves), 0.1 (light-blue curves), 0.15 (dark-blue curves), and 0.2 (purple curves)  $P/P_0$ . (b) Discrimination of water, methanol, and ethanol vapors using principal-components analysis (PCA).

Adapted with permission from Reference 65.

of the scales act as a diffraction grating, together combining multilayer interference from individual reflectors and diffraction from the array of these reflectors (133). Spectral measurements of the scales in the visible range provide information about the nature and concentration of the vapors, allowing for the identification of closely related vapors such as water, methanol, and ethanol with a single sensing structure. The chemical selectivity of response of these photonic structures was examined by exposing an  $\sim 5 \times 5$ -mm region of the wing to a variety of vapors presented individually at different concentrations and by monitoring the differential reflectance spectra. **Figure 14a** illustrates the differential reflectance spectra of scales upon exposure to water, methanol, and ethanol vapors. The differential reflectance response patterns of the scales to these closely related vapors were very diverse. The most pronounced spectral differences were at 325–500 nm and in response magnitude at 500–600 nm. To differentiate these responses quantitatively, multivariate spectral analysis such as PCA was applied (**Figure 14b**). PCA demonstrated that three tested vapors were perfectly differentiated, even at the lowest tested vapor partial pressure.

## 4.2. Structurally Colored Colloidal Crystal Films Based on Core/Shell Nanospheres

The 3-D-ordered arrays of colloidal nanoparticles with cubic-close-packed or face-center-cubic structures are very common in nature as natural opals and inspire numerous technological applications (139). Artificial self-assembled structures based on the principles of natural opals have been



**Figure 15**

Selective detection of vapors using a single structurally colored colloidal crystal film formed from composite core/shell nanospheres. (a) Differential reflectance spectra for four vapors [water, acetonitrile (ACN), dichloromethane (DCM), and toluene] of increasing partial pressure ranging from 0 to 0.07  $P/P_0$ . Vapor concentrations are 0 (gray dashed lines), 0.02 (red curves), 0.04 (gold curves), and 0.07 (blue curves)  $P/P_0$ . (b) The multivariate response of the colloidal sensor film for four tested vapors. Multivariate analysis was done by using PCA tools by processing differential reflectance spectra over the 700–995-nm range. Arrows indicate the increase in concentrations of each vapor. Vapor concentrations are 0, 0.02, 0.04, and 0.07  $P/P_0$ . Adapted with permission from Reference 64.

extensively used for chemical sensing (64, 140–143). Traditionally, for monitoring of multiple analytes, individual photonic crystal sensing films are combined in an array in which each film has partial response selectivity to a certain class of analytes (142). To reduce or even overcome the need for the construction of sensor arrays, selective sensing of multiple vapors was demonstrated on the basis of the structurally colored colloidal crystal films formed from composite core/shell nanospheres (with a 326-nm-diameter polystyrene core and a 20-nm-thick sol-gel shell) (64). The vapor-sensing selectivity was provided by the combination of (a) the composite nature of the colloidal nanospheres in the film and (b) multivariate analysis of the spectral changes in the film reflectivity upon exposure to different vapors. In these sensors, the detection mechanism is based on the change in the optical lattice constant of the colloidal crystal arrays as a function of analyte concentration; such a change leads to the variation in the shape of the Bragg diffraction band. To evaluate the response of the sensor, several model vapors of different polarity such as water, ACN, DCM, and toluene were selected (Figure 15). Changes in the differential reflectance spectra of the sensing film upon exposure to different vapors at various concentrations illustrate several important findings (Figure 15a). For polar vapors such as water and ACN, the differential reflectance spectra have a stable baseline and consistent well-behaved changes in the reflectivity as a function of analyte concentration. The response of the colloidal crystal film to nonpolar vapors such as DCM and toluene is quite different from the response to polar vapors. There are



pronounced analyte concentration-dependent baseline offsets that are likely due to the distortions of the optical lattice upon exposure to nonpolar vapors. These distortions are likely caused by the reversible slight swelling of the core of the nanospheres by the vapors. Discrimination of vapors using a single sensing colloidal crystal film was done through PCA (**Figure 15b**). The best selectivity was obtained between toluene and DCM vapors, whereas water and ACN vapors were almost unresolved.

## 5. MAJOR DIRECTIONS IN DEVELOPMENT AND APPLICATION SCENARIOS

The current and intended future implementations of vapor sensors can be summarized as installations into stationary infrastructure (e.g., interiors of residential and commercial buildings, industrial infrastructure), integration into nonstationary platforms (e.g., desktop analytical instrumentation, transportation vehicles, home appliances), integration into handheld or wearable components (e.g., pocket detectors, mobile phones, active wear), and single-use installations (e.g., medical and food packaging). The acceptance of vapor sensors deployed in these implementations relies on the ongoing and future technological advances toward new broad application scenarios such as (a) wireless sensing, (b) battery-independent sensor operation, (c) distributed sensor networks, and (d) unobtrusive sensor designs.

### 5.1. Wireless Sensing

The trend toward wireless sensing is driven by several key advantages of wireless sensors over traditional tethered sensors. Benefits of wireless sensors include the unobtrusive nature of sensor installations, higher nodal densities, and lower installation costs without the need for extensive wiring. Depending on the sensor design and mode of operation, wireless sensors can be categorized as active and passive. Active wireless sensors have on-board power to perform sensing and signal transmission. Passive wireless sensors lack on-board power and receive their power from the electromagnetic field generated by the sensor reader. Wireless sensors that adapt wireless communication concepts originally developed for radio-frequency identification (RFID) tags are also known as RFID sensors (144), with growing interest in the application of near-field communication protocols for wireless sensing (60). Most of the transducers that have been developed have also been implemented in wireless sensors (4).

### 5.2. Battery-Independent Sensor Operation

The trend toward battery-independent sensor operation is driven by opportunities that could be provided in sensor operation without the need for a battery and is inspired by the technological advances in the area of power scavenging (harvesting) (145, 146). At present, the power consumption of the most widely used vapor sensors, such as metal oxide semiconductor (MOS) sensors, is 30–400 mW (147, 148). Although such power requirements are often not an issue for tethered sensor implementations, they are unacceptable for the long-term wireless installations of sensors. Thus, sensors that require much less or no on-board power and simultaneously provide the same performance as or better performance than available MOS sensors are highly desired and are under development, including those with self-heating capabilities (149). With the reduction of required power for sensor operation, new opportunities arise to harvest power from the available ambient sources.

To properly assess the power requirements for a wireless vapor sensor, it is critical to take into the account not only the power needed for the operation of different transducers, but

also the power needed for the operation of the wireless transmitter. Different types of energy-harvesting devices provide different amounts of energy, e.g., from an ambient radio-frequency background ( $\sim 0.001 \text{ mW cm}^{-2}$ ), human/industrial motion and vibrations ( $0.005\text{--}0.5 \text{ mW cm}^{-2}$ ), human/industrial heat ( $0.05\text{--}10 \text{ mW cm}^{-2}$ ), and indoor/outdoor light ( $0.01\text{--}50 \text{ mW cm}^{-2}$ ) (145, 146). Depending on the desired wireless communication distance, data rate, and other specifications, the needed power for a typical distance of wireless communication is, for example, 30 mW (ZigBee, 10–75 m), 2.5–100 mW (Bluetooth, 10–100 m), and 25  $\mu\text{W}$  (MICS,  $\sim 2$  m) (150).

### 5.3. Distributed Sensor Networks

Arranging individual sensors into a distributed set to form a sensor network is gaining acceptance for a wide variety of sensing applications, including vapor sensing, in which sensors are implemented in their wireless configurations (60, 151, 152). Wireless sensor networks (WSNs) provide valuable spatially resolved, distributed information that cannot be obtained by using tethered sensors. One of the most critical challenges of WSNs for vapor sensing is the power consumption of individual sensors (see Section 5.2). Another critical challenge of WSNs for vapor sensing is the insufficient selectivity of existing sensors and sensor arrays (4). As in conventional tethered sensor systems, minimizing the number of wireless sensors in an array is attractive because it simplifies data analysis, reduces data-processing noise, and simplifies sensor material deposition and device fabrication. However, for a wireless sensor node device, minimizing the number of sensors in an array brings the additional critical benefit of minimizing the required power.

### 5.4. Unobtrusive Sensor Designs

The trend toward unobtrusive sensor designs is driven by opportunities that could be provided in the operation of sensors that are either micro- or nanosized, flexible, or fabric integrated. This trend is inspired by technological advances in the areas of sensor nanofabrication (153), flexible (154, 155) and stretchable (156) sensors, and printed/flexible electronics (154, 157). Potential applications of such unobtrusive sensor designs range from implanted and in vivo sensors (114) to smart tattoo (156) and smart food label (158, 159) sensors to wearable sensors (150) with different sensor-readout methods, including readout of multivariable electronic (160) and optical (161) sensors in smartphone and other mobile devices.

## 6. OUTLOOK

To achieve vapor-response selectivity of sensors desired for numerous applications, it is critical to combine the proper materials with a multivariable transducer. Such combination provides the ability to perform selective vapor measurements without the need for a sensor array. Such simplification of the sensor system design becomes important for applications in which power requirements, manufacturability, and unobtrusive sensor design are critical. The two new types of sensing materials described here, bionanomaterials and bioinspired nanostructures, have the strong potential to significantly improve selectivity of field-operated sensors. The materials critically reviewed here are compatible with different types of transducers, providing the ability to tune the sensor design to certain practical implementations in which the type of sensor readout is important, for example, for visual self-reporting sensors and for integration with existing electronic device infrastructure.



## DISCLOSURE STATEMENT

The authors are not aware of any affiliations, memberships, funding, or financial holdings that might be perceived as affecting the objectivity of this review.

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